

# International Agreement Report

# Natural Circulation (Interruption) Analysis with MELCOR 2.2 during Asymmetric Cooldown Transients

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# ABSTRACT

This document describes the analysis carried out with MELCOR 2.2 computer code of the natural circulation (interruption) phenomena during asymmetric cooldown transients in a 3-loop nuclear power plant (NPP) configuration. Indeed, thermal-hydraulic analysis is an important issue for severe accident codes, it constitutes the starting point of the analysis before the occurrence of the core degradation.

The considered accident scenario consists in a feedwater line break (FWLB) combined with loss of offsite power (LOOP) in a generic 1000 MWe 3-loop pressurized water reactor (PWR).

For this study, a Bel V MELCOR 3-loop PWR model has been developed. The main goal is to verify the capabilities of the MELCOR code in predicting the establishment of the natural circulation flow regime, the eventual occurrence of the natural circulation interruption (NCI) phenomena and to compare to the results from an equivalent analysis performed using the thermal-hydraulic system code CATHARE. The activity is completed by carrying out sensitivity analyses in order to identify the key MELCOR modeling parameters.

The calculation results confirm the Bel V MELCOR 3-loop plant model capability and suitability for its intended purpose in support of regulatory activities.

### FOREWORD

MELCOR is a fully integrated, engineering-level computer code that models the progression of severe accidents (SA) in light water reactor (LWR) nuclear power plants. A broad spectrum of severe accident phenomena is treated in MELCOR in a unified framework. Among these, the thermal-hydraulic (TH) response in the reactor coolant system is addressed in the current study. MELCOR is the reference code used by Bel V for severe accident analyses, and, to date, it has been mainly used in the framework of Bel V R&D program.

Belgium and US have signed an agreement on Cooperative Severe Accident Research Program (CSARP). Bel V is responsible for the CSARP agreement in Belgium since 2012.

Bel V is acting, since 2008, as a subsidiary of the Belgian Federal Agency for Nuclear Control (FANC). Bel V groups nuclear experts who are performing activities in the area of nuclear safety and radiation protection. Its mission is to contribute to the safety of the population and of the environment.

This report was prepared to share the code application experience with other CSARP members.

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# **EXECUTIVE SUMMARY**

This document describes the analysis carried out using MELCOR 2.2 code of the natural circulation (interruption) phenomena during asymmetric cooldown transients in a 3-loop nuclear power plant (NPP) configuration. Indeed, thermal-hydraulic (TH) analysis is an important issue for severe accident codes since it constitutes a starting point of the analysis that precedes the core degradation occurrence.

The considered scenario consists of a feedwater line break (FWLB) accident combined with loss of offsite power (LOOP) in a generic 1000 MWe 3-loop pressurized water reactor (PWR).

When the primary forced flow is lost, the nuclear reactor core decay heat is generally removed through natural circulation (NC) convection: the flow is driven by the coolant density differences in the steam generators (SGs) (heat sink) and in the reactor vessel (heat source).

In such conditions, with one affected SG which is emptied and isolated on its secondary side SG, a cooldown procedure at prescribed cooldown (and depressurization) rate is started. In general, the emergency response guidelines (ERG) limit the cooldown rate in a range that prevents steam bubble formation under the reactor vessel head. However, under asymmetric cooldown conditions between the RCS loops, natural circulation interruption (NCI) might occur in the inactive (i.e., non-cooling) loop. This scenario may prevent the reactor coolant system (RCS) to reach the entry conditions for the residual heat removal system (RHRS).

For this study, a MELCOR 3-loop PWR model has been developed. The main goal is to verify the capabilities of the MELCOR code in predicting the natural circulation interruption (NCI) phenomena and to compare to the results from an equivalent CATHARE calculation. The activity is completed by carrying out sensitivity analyses, performed in order to identify the key MELCOR modeling parameters.

The results of the CATHARE model which was validated against (among other) experimental data in the framework of experimental projects like PKL and ROSA and on plant available data, are considered as reference in the current study.

It is noted that some boundary conditions are selected for comparison purposes only and might not represent real plant cases.

The calculation results show:

- the MELCOR 3-loop plant model capability to simulate NC(I) phenomena, as well as the correctness of the implemented modeling assumptions;
- the sensitivity of the NC(I) phenomena (at least/mainly) to the conditions that could lead or not to the occurrence of the NCI phenomenon such as the decay heat level (conservative vs best estimate or time after scram) and RCP resistance value.

To conclude, the calculation results confirm the Bel V MELCOR 3-loop plant model capability and suitability for its intended purpose in support of regulatory activities.

# ABBREVIATIONS AND ACRONYMS

ADV	Atmospheric Discharge Valve
AFW	Auxiliary Feed Water
Bel V	Belgian Technical Support Organization
CF	Control Function
CL	Cold Leg
CVCS	Chemical and Volume Control System
CVH	Control Volume Hydrodynamics (MELCOR Package)
DC	DownComer
EOT	End of Transient
ERG	Emergency Response Guideline
FW	Feed Water
FWLB	Feed Water Line Break
HL	Hot Leg
LOOP	Loss of Offsite Power
LSTF	Large Scale Test Facility
LWR	Light Water Reactor
MSIV	Main Steam Isolation Valve
NC	Natural Circulation
NCI	Natural Circulation Interruption
NPP	Nuclear Power Plant
PKL	Primär-KreisLauf
PRZ	Pressurizer
PWR	Pressurized Water Reactor
RCP	Reactor Coolant Pump
RCS	Reactor Coolant System
RHRS	Residual Heat Removal System
ROSA	Rig-of-Safety Assessment
RPV	Reactor Pressure Vessel
RV	Relief Valve
SA	Severe Accident
SD	Steam Dump to Condenser
SG	Steam Generator
SOT	Start of the Transient
SV	Safety Valve
TH	Thermal-Hydraulic
TU	Turbine
UH	Upper Head

# 1 INTRODUCTION

This document describes the MELCOR 2.2 TH code analysis of the NC(I) during asymmetric cooldown transients in a 3-loop NPP configuration. The objective is to assess the TH capability of the code during the transient period that precedes the core degradation phase. MELCOR is the reference code used by Bel V for severe accident analysis, and, to date, it has been mainly used in the framework of the Bel V R&D program.

#### 1.1 Background

The considered scenario consists in a FWLB accident combined with LOOP in a generic 1000 MWe 3-loop PWR. Actually, when the primary flow is lost, the nuclear reactor core decay heat is removed through NC convection: the flow is driven by the coolant density differences in the SGs (heat sink) and in the reactor vessel (heat source).

In such conditions, with one affected SG which is emptied and isolated on its secondary side SG, a cooldown procedure at prescribed cooldown (and depressurization) rate is started. In general, the emergency response guidelines (ERG) limit the cooldown rate in a range that prevents steam bubble formation under the reactor vessel head. However, under asymmetric cooldown conditions between the RCS loops, NCI might occur in the inactive (i.e., non-cooling) loop. This scenario may prevent the RCS to reach the entry conditions for the residual heat removal system (RHRS), i.e. RCS temperature of 450 K.

In particular, the NCI occurrence in the loop with the affected (emptied) SG (SG-A) and RCS pressure of 3 MPa on its secondary side is the result of a counter-buoyancy force buildup in its U-tubes. Due to continuous decrease of the temperature in the hot leg, a negative temperature difference between the ascending and descending part of the SG-A U-tubes will take place leading to a progressive flow decrease. Flow stagnation will occur if the counter driving forces balance the driving force over the reactor vessel.

Actually, as pointed out in [1][3], a stagnant loop may hinder the overall RCS cooling process and the transient may evolve toward a degenerated state. Some recent experimental and analytical studies [1][2][3] identify the number of affected (non-cooling) loops as well as the secondary side conditions as the main parameters in determining the cooldown rate that maintain NC in the affected loops. The mentioned studies show that in some cases, the RHRS entry conditions could not be reached, i.e. RCS temperature of 450 K, notwithstanding the fact that NC is maintained in the intact loop(s).

The above mentioned experimental and analytical activities are the starting point of this study. The selection of the scenarios to be investigated by means of MELCOR severe accident code is based on the calculation results obtained by the advanced TH system code CATHARE 2/V2.5\_2/mod8.1 1 developed by CEA, EDF, AREVA, and IRSN. Using CATHARE NC(I)-study explorations, for the current comparison activities only a selection of accident scenarios is analyzed (i.e. not all the CATHARE studies are repeated).

#### 1.2 Objective

The objectives of this study are:

- to assess the MELCOR capabilities in predicting correctly the establishment of the NC flow regime.
- to verify whether or not the NCI phenomena is reproduced by MELCOR and, if it is the case, on which modeling conditions
- to investigate how sensitive are the MELCOR modeling key parameters on the simulation results; the input parameters to be varied are selected in order to get MELCOR calculation results close to the CATHARE ones
- to confirm the Bel V MELCOR 3-loop PWR model capabilities in simulating important phenomena (i.e. *NC and NCI in this particular case*)

A MELCOR-CATHARE comparison for a RCP trip transient (LOOP), performed by using the developed reference 3-loop input deck, completes the analysis.

It is noted that CATHARE results are considered as reference data for MELCOR calculations since the 3-loop PWR Bel V CATHARE model has been validated against experiments carried out in integral test facilities 123 and on plant available data.

#### 1.3 Outline of the Report

In this study, MELCOR and CATHARE calculation results, simulating NC(I) phenomena during asymmetric cooldown transients, are compared. The accident scenario is described in §0. The MELCOR model of the 3-loop PWR is described in §1.

The results of the comparative analyses are reported in §0. It includes steady-state and transient results of the FWLB cases and their related sensitivity studies and also the simulation of the single-phase NC test which completes the study.

It is noted that some boundary conditions are selected for comparison purposes only and might not represent real plant conditions.

The major results of the analyses are summarized in the conclusions section §1:

- MELCOR capability to simulate NC(I) phenomena is assessed, confirming the suitability of the selected transient for MELCOR plant model for analyzing such transient scenarios.
- The modeling conditions on which CATHARE calculations can be reproduced by MELCOR are identified.
- The most influencing parameters on the NCI are identified and analyzed through sensitivity studies.
- Further studies will be performed (depending on the interest and availability of resources):
  - Additional comparisons with available thermal-hydraulic calculation results.
  - Further model improvements based on comparative analyses, due to code modeling progress.
  - Extend the analysis to core melt accidents.

The calculation results confirm the Bel V MELCOR 3-loop plant model capability and suitability for its intended purpose in support of regulatory activities.

Two appendixes report the figures of the comparisons MELCOR-CATHARE for the base case for FWLB and for the RCP trip transient.

# 2 ACCIDENT SCENARIO DESCRIPTION

The first part of the calculation (time < T1) is dedicated to the steady-state stabilization of the system (i.e. no variation of relevant system variables during the calculation) which is followed by the accident initiator and transient conditions.

The transient consists of a FWLB accident combined with a LOOP (i.e. FWLB at t = T1 and LOOP at t = T2) as described in Table 2-1. The analyses are performed starting from the nominal parameters (e.g. temperature and pressure) corresponding to nominal power rate of 3000 MWth. According to MELCOR best practices 5, end of cycle decay heat based on real cycle data is used for the reference case.

The accident scenario can be divided into four phases delimited by key events occurring at times T1, T2, T3, and T4 as follows:

- 1. <u>Steady-state stabilization (T < 0s)</u>: stabilization of the system at full power
- 2. Depressurization of the broken SG (0-50s): from the SOT up to scram

At time T1 = 0 s (SOT), a full rupture in the main feedwater line of SG-A occurs. The rapid depressurization and emptying of SG-A also entrains the depressurization and emptying of SG-B and SG-C via the common steam header and the steam lines, prior to MSIV closure. The reactor trip is assumed to occur at time T2 = 50 s when the low-low level signal in one of the intact SG is generated.

3. <u>System stabilization</u> (50-20000s): up to the start of the cooldown procedure by the operator

At the time of reactor trip, the RCPs are assumed to be lost (because of LOOP), the steam lines are isolated via their MSIVs, and the AFW to SG-B and SG-C is started without delay. The ADV of SG-B and SG-C evacuates the core decay power until the operator starts the cooldown. Around 2.5 h after the onset of the accident, the mass inventory is restored in SG-B and SG-C. The system is left to stabilize until time T3.

4. Cooldown phase (20000-80000s): up to EOT

At T3 = 20000 s, the operator starts the cooldown by using the ADV of SG-B and SG-C to bring the RCS to RHRS entry conditions. Since the primary loop flow rate due to NC is rather low and thus the loop transit time is rather high, the operator needs to wait for several minutes to evaluate the effective primary cooling rate (based on the measure of the cold-leg temperature evolution of the cooling loop) and to perform eventual corrective actions.

5. End of transient (80000s)

At T4 = 80000 s, the simulation ends. This is the same duration as in the case of CATHARE. RHRS entry conditions are checked in the results of the calculations.

Specific modeling assumptions adopted in the base case (A) and sensitivity studies (B to E) are described in the following sections.

#### 2.1 <u>Operator Actions</u>

In all cases, the cooldown phase is initiated by the operator (imparted event in the simulations) to ensure a prescribed RCS temperature decrease rate of 12 K/h<sup>1</sup>.

In MELCOR, the cooldown phase is simulated by a control function (CF) which uses the temperature input of CATHARE to determine the desired ADV opening fraction.

#### 2.2 MELCOR Initial and Boundary Conditions: Base Case (A)

The initial and boundary conditions considered in the current simulations are as follows:

- 1. The main feedwater is simulated until time T1.
- 2. The reactor trip occurs at the low-low level signal in one of the intact SG, which is however imposed by the user at T2 = 50 s.
- 3. The LOOP is assumed to occur at the time of reactor trip. The RCP coast-down is modeled according to plant available data, see Figure 2-1.
- 4. The isolation of the steam lines is assumed to occur at the time of reactor trip.
- 5. The AFW system starts delivering water to SG-B and SG-C 25s after reactor trip occurs (10 s after is fully isolated).
- 6. After time T3 (20000 s), the operator cooldown actions are simulated.
- 7. The target cooldown rate is 12 K/h.
- 8. The SG ADV setpoints are modified to keep the SG at a prescribed pressure before time T3, in order to match CATHARE results.

#### 2.3 <u>Sensitivity Analyses Definitions: Cases B to D</u>

The timing and occurrence of NCI depend upon several modeling parameters 123, such as the initial loop flow rate at the beginning of the cooldown phase, the status of the SGs (empty or filled) at the start of the cooldown, the number of active SGs, the initial core decay power, and the operator actions with respect to the cooldown rate.

The considered sensitive cases are listed in Table 2-3. The objective is to identify the most sensitive MELCOR modeling parameters with respect to the NCI occurrence as:

- 1. the cooldown rate, to identify the cooldown gradient limit under which NC in the inactive loop(s) is maintained;
- 2. the decay heat (or time after scram), to identify which one between the best estimate (based on a real plant cycle and ORIGEN calculation results) and conservative (the one used for the design basis accident licensing studies) values for the core decay heat are conservative with respect to the NCI phenomena occurrence. The decay power input is shown in Figure 2-2.

An additional case is studied to verify the occurrence or not of the NCI phenomena, in case the RCP resistance is set to zero. This allows verifying whether or not the way in which the pump resistance is modeled could impact the occurrence of the NCI. Thus the only modification with

<sup>&</sup>lt;sup>1</sup> The value of 12 K/h is not prescribed by the procedures but assumed for the calculations.

resistance is modeled could impact the occurrence of the NCI. Thus the only modification with respect to the base case, in addition to the cooling rate, is the pump resistance factor which is set to zero.

#### 2.4 Additional Case E: Single-phase NC

This case was considered in order to assess the capability of the developed 3-loop MELCOR plant model, to correctly predict single-phase NC phenomenon against experimental data. The validation was performed by comparing the MELCOR simulations results with the CATHARE simulation results of an experimental RCP trip transient. The CATHARE calculation results are considered herein as reference (also in this case) in the comparisons against MELCOR. The main events of case E are reported in Table 2-2.



Figure 2-1 RCP Coast-Down Input



Figure 2-2 Decay Power Input: Conservative (Red) and Best Estimate (Blue)

Table 2-1	Main Events of the Base Case (	(and Cases B to D)
		. ,

Phase/Event	Time or Time Span	Description		
Phase 1	time < 0 s	Steady-state stabilization		
Event T1	time = 0 s *	FWLB in SG-A		
Phase 2	0 s < time < 50 s	Depressurization and emptying of all SGs		
Event T2	time = 50 s*	Reactor trip, MSIVs closed, shutdown of RCPs due to LOOP		
Phase 3	50 s < time < 20000 s	SG-B and SG-C refilling and RCS stabilization		
Event T3	time = 20000 s *	Operator starts cooldown at prescribed cooling rate using ADV of SG-B and SG-C		
Phase 4	time > 20000 s	Cooldown to RHRS entry conditions		
Event T4	time = 80000 s	End of calculation		

\* Imparted event

Event	Time or Time Span	Description
Phase 1	time < 0 s	Steady-state stabilization
Event 11	time = 0 s *	RCPs trip
Phase 2	0 s < time < 160 s	RCPs coast-down
Event T2	time = 2 s * time = 160 s	Reactor trip on RCP low-low speed End of RCPs coast-down
Phase 3	160 s < time < 800 s	Single phase NC
Event T3	time = 800 s	RCPs restart
		End of calculation

#### Table 2-2 Main Events of the Single-Phase NC Test, Case E

\* Imparted event

Table 2-3	List of Ca						
Run	Туре	Cooldown Rate [K/h]	RCP resistance factor [-] <sup>\$</sup>	Decay heat	Notes		
A Base ca	ase: REFEREN	NCE					
BC	Reference	12	4.20e-4	Best estimate	Comparison against CATHARE		
B Sensitiv	vity study: im	pact of cooling	rate on NC(I) or	ccurrence			
B1	Cooling rate	10	4.20e-4	Best estimate	Comparison against CATHARE		
B2	Cooling rate	14	4.20e-4	Best estimate			
C Sensitiv	vity study: im	pact of decay h	eat * on NC(I) tr	ansition			
C1	Decay heat	12	4.20e-4	Conservative			
C2	Decay heat	24	4.20e-4	Conservative			
C3	Decay heat	26	4.20e-4	Conservative			
C4	Decay heat	28	4.20e-4	Conservative			
D Sensitiv	vity studies: ii	mpact of RCP r	esistance set to	zero on NC(I) tra	ansition		
D1	NO RCP resistance	34	0	Best estimate			
D2	NO RCP resistance	36	0	Best estimate			
E Single	E Single phase NC study						
E	NC test	-	4.20e-4	Best estimate			
§ See §3.2.	1 for more inform	mation					
* Or time a	* Or time after scram						

# 3 MELCOR MODEL OF THE 3-LOOP PLANT

MELCOR is a fully integrated, engineering-level computer code that models the progression of severe accidents in light-water reactor NPPs. MELCOR is being developed at Sandia National Laboratories for the U.S. NRC as a second-generation plant risk assessment tool and the successor to the Source Term Code Package (STCP). A broad spectrum of severe accident phenomena in both BWRs and PWRs is treated in MELCOR in a unified framework. These include TH response in the RCS, reactor cavity, containment, and confinement buildings; core heat-up, degradation, and relocation; core-concrete attack; hydrogen production, transport, and combustion; fission product release and transport behavior [9,10,12].

MELCOR TH models are common for the whole code, and thus are used for both RCS and containment. The discretized hydrodynamic equations are formulated in a form that conserves mass and energy to a high level of accuracy. The numerical solution method is based on a semi-implicit solution of the equations, and the time step is therefore subject to the material Courant limit. Sources, sinks, and other modifiers are calculated by closure relations and additional auxiliary models that are generally nonlinear [12].

The latest development release, i.e. MELCOR 2.2.9607, has been used for the current analysis.

#### 3.1 <u>Overview</u>

The creation of a plant model is an interactive procedure which includes the selection of a nodalization<sup>2</sup> diagram, preparation of the code input deck, and documentation of these activities 16. For the current activity a 3-loop 3000 MWth PWR plant model has been developed for MELCOR 1.8.6 code version, and then converted for MELCOR 2.1, thanks also to the availability of similar studies like 461120. No changes were needed to switch from the 2.1 to the 2.2 version [5, 9, 10].

In particular, an existing MELCOR input deck of a generic 4-loop PWR has been 'adapted' to the selected plant. The following main assumptions were adopted for the development of the plant input deck:

- same subdivision of the input deck in separated files
- similar 'noding' of the components
- similar structure of the CFs
- the behavior of several systems is currently modeled, including flags and set-points added as CF for activation (or not)

The main modeling effort has been spent in the:

- stabilization at full power
- COR package: plant data converted into the plant input deck
- containment modeling (not addressed in this study)

The plant model is suitable for steady-state and transients calculations (i.e. it is able to calculate the accident sequences).

<sup>&</sup>lt;sup>2</sup> *Nodalization/nodalization diagram.* Spatial discretization of the two-phase flow field, in which equations are solved, is organized in control volumes connected by junctions and it is called nodalization. Sometimes the meaning of the word nodalization is extended to the whole set of parameters and information supplied by the user. Nodalization diagram is a drawing or illustration showing control volumes with their connecting junctions. *Definition from 7.* 

The developed input deck of a 3-loop PWR comprises, see Figure 3-1:

- Vessel and Reactor Coolant System,
- Reactor Coolant Pumps,
- Pressurizer
- Steam Generators
- Primary and Secondary System Relief Valves
- Feed-Water and Auxiliary Feed-Water Systems
- Charging and Volume Control System
- Natural Circulation Modeling
- Decay Heat Power Modeling (best estimate based on a real plant cycle and ORIGEN calculation results)
- Accumulators (not addressed in this study)
- Safety Injection System (not addressed in this study)
- Core Degradation Modeling (not addressed in this study)
- Containment (not addressed in this study)
- Auxiliary Building (1 CV) (not addressed in this study)

#### 3.2 Main Modeling Assumptions

Only the main modeling assumptions impacting this study are described below.

#### 3.2.1 RCP Model

The primary pumps, rated at 5.3 MWth each, circulate 4600 kg/s of coolant per loop with a net pump head of 0.56 MPa.

In the CATHARE input deck, the pump is modeled by using the homologous curves.

QUICK-CF pump model is implemented in the flow path (FL) package of the plant input deck. The model simply uses a user-defined CF to calculate the pressure head the pressure developed by a pump (in Pa). All control logics must be included in the CF that has been constructed to yield a homologous pump model similar to that used in CATHARE and RELAP of the selected 3-loop plant model.

The model is numerically explicit; that is, the pressure head is based on conditions at the start of the MELCOR system timestep and remains unchanged throughout the step, even if the CVH package is sub-cycling [9,10].

In practice in MELCOR the pump is modeled as  $\Delta p$  (loss term). The resistance is modeled by CFs: "negative pump" to simulate friction losses behavior (i.e. negative  $\Delta p$ ).

In the present case:

- the RCP coast-down is modeled according to plant available data, see Figure 2-1; and
- the RCP resistance is "*adjusted*" to get a similar NC mass flow rate of CATHARE before the start of cooldown.

The new pump models UNIV and HOM are out of the scope of the present study, and might be subject to further study.

To interpret the value of the pump resistance in Table 2-3, the value reported in the column is to be multiplied to 6.9E5 Pa. Like this, the pump resistance is given in terms of pressure. The resistance value has been calibrated on the basis of the CATHARE results (which are considered as reference because validated on experiments), and then verified on the NC case E.

The RCP resistance is one of the modeling assumptions most influencing the phenomena investigated in the current study, i.e. NC and NCI.

#### 3.2.2 Steam Generator

The SGs are of the inverted U-type design. The U tube bundle consists of 5350 Inconel tubes with a 19 mm outer diameter, and a nominal heat transfer area of 6250 m<sup>2</sup>. The nominal recirculation ratio is about 3.

The several vertical U-tubes with different elevations are modeled as follows:

- MELCOR: the U-tubes are lumped into one equivalent U-tube having the mean elevation and the same total heat exchange area.
- CATHARE: 3 elevations are considered in order to take into account the effects of the longest and shortest tubes. In this case the inlet and outlet zones of the SGs are modelled as VOLUME component in order to take into account the connections to the different U-tubes. Also other cases considering different U-tube elevations have been studied in the past, see [1, 2, 3, 22].

Previous studies showed that the number of equivalent tubes (e.g. 1 vs 3) may slightly impact the time of NCI occurrence.

#### 3.2.3 Cooldown Procedure

The plant modeled in this study is a "cold reactor vessel head", this means that the bypass flow to the reactor vessel head is designed in such a way to keep the upper head temperature at the cold leg temperature as long as the RCP are running. Together with the heat exchange out of the vessel upper head, the cooling and depressurization rate of the primary circuit and the number of active SGs impact the vapor formation in the upper head in case of a cooling/depressurization transient under NC flow conditions.

The ERG addressed in this study allows the cooling and depressurization of the primary circuit without vapor formation in all the parties of the primary circuit and more particularly the vessel upper head and the SG U–tubes apex. On the basis of the analysis of the transient cooling/depressurization based on the experience on PWR, limits on the cooldown rate in case of NC have been defined. In particular, the limitations on the cooldown rate and minimum subcooling to prevent vapor formation have been defined.

The previous version of the ERG procedure of the analyzed plant limits the cooldown rate to prevent steam bubble formation under the reactor vessel head during the depressurization, and a clear statement about the strategy to be followed to prevent NCI occurrence was lacking. In the most updated version, there is also a warning saying that in case of an inactive loop, the maximum cooldown is more restrictive to avoid the stagnation in this inactive loop. An inactive loop is defined as a loop which does not allow evacuating the heat by means of its SG.

In general, the operator is quite free to adopt an appropriate cooldown strategy: stepwise, gradual, or continuous cooldown. For that reason, there is a large source of uncertainty in determining an adequate cooldown procedure. This specific point has been thoroughly analyzed by Bel V by means of CATHARE code, e.g. in [1, 2, 3].

The cooldown period ends when the entry conditions for the RHRS connection are reached in each loop, i.e. HL temperatures become lower than 450 K [1].

In MELCOR the cooldown is performed by a series of CFs which models the ADV valve opening fraction on the basis of the temperature difference between the atmosphere in SG secondary side and a reference temperature. To reduce uncertainties in the results interpretation, the reference cooldown temperature is taken directly from CATHARE results.

The following input assumptions are adopted:

- ADVs in SG-B and SG-C perform the function of cooldown at a prescribed rate (at imposed temperature from CATHARE results) from 5.5h on.
- To keep the SG pressure at prescribed level like in CATHARE results before the manual activation of the ADVs (before 5.5h), the SV setpoint is modified to match the CATHARE SG pressure. No further modifications have been done, since the steady-state results were satisfactory.

#### 3.2.4 Decay Heat

Previous CATHARE calculations were performed with conservative decay heat 1. However in the current study, the MELCOR best estimate decay heat based on real cycle data at the end of life is considered. This input parameter, together with the cooling rate, has a major impact on NCI cooldown rate value prediction.

It is noted that since the decay heat level is the key parameter, the same conclusions can be achieved by varying the time of cooldown after scram.



Figure 3-1 MELCOR 2.2: 3-Loop PWR Reactor Coolant System Hydrodynamic Nodalization

# 4 RESULTS OF THE ANALYSES

The methodology followed in the analyses has been developed for system TH codes. It is based on a number of references on the subject [13, 8, 14, 15, 7].

Thus, the acceptable errors stated in the above mentioned references and the degree with which the methodology are followed, might not be amenable to rigorous validation of SA codes.

Furthermore, modelling of phenomena for extreme conditions involving the prediction of extreme physical behavior, like the ones expected in SA domain, is often subject to great uncertainties 18 (out of scope for the current study).

Enormous progresses have been made during the last two decades in the understanding of SA phenomena; however, the qualification level of results from SA analyses shall be considered far lower than the qualification level expected or achieved in the area of system thermal hydraulic analyses 7.

This stresses the need of having a good validation basis as much as possible according to the accident progression phase.

#### 4.1 <u>Steady-State Results</u>

According to 13, a nodalization representing an integral test facility or a plant can be considered qualified at steady-state level when it:

- has a geometrical fidelity with the involved system3, and
- is reproducing the measured nominal steady-state condition4 of the system.

Regarding the first aspect, MELCOR plant input deck has been developed according to the CATHARE plant model, which is considered as reference for model development because it has been validated against experiments.

Regarding the second aspect, the MELCOR plant input deck is stabilized at full power after a steady-state of 3000 s. Only a summary of the steady-state results is reported here:

- the MELCOR pressure and pressure drops for the RPV and loop 1 are reported in Figure 4-1 together with reference data in red, when available;
- a summary of the main important quantities is reported in Table 4-1, which includes the acceptable errors, according to [8, 13, 14].

<sup>&</sup>lt;sup>3</sup> The first item "*geometrical fidelity with the involved system*" consists of a systematic comparison between the quantities (i.e., volumes, surfaces, lengths and masses), which demonstrates the adequacy of the model in representing the real system.

<sup>&</sup>lt;sup>4</sup> The second item "*reproducing the measured nominal steady-state condition*" is the properly defined steady-state qualification (see also 8 and 14). This step requires the comparisons between experimental measures (or, as in this case, with the plant quantities and/or calculated reference results – CATHARE in this case – when plant data are not available) and the calculated results at the beginning of the transient. The selection of the key parameters covers the relevant quantities for evaluating the steady-state conditions.

The following considerations are valid for Table 4-1:

- The percent difference [%] with respect to the reference value (plant data or reference calculations) is calculated as the ratio:
  - |reference value calculated value| / |reference value|
- The steadiness of the steady-state is checked qualitatively from figures (not reported here)
- Other quantities are checked and compared with reference data (plant data or reference calculations), e.g. the results of other calculations (not reported here)
- No noticeable differences were found between the steady-state results of MELCOR 1.8.6, MELCOR 2.1 and MELCOR 2.2 (not reported here)

Considering (among other) the acceptability criteria set forth in 13, Table 3 of 8 and Table 2 of 14 developed for TH codes, it can be concluded that the MELCOR plant nodalization results are satisfactory at the steady-state level.



#### Figure 4-1 MELCOR Pressure and Pressure Drops RPV (Left) and Loop A (Right) and Indication of Available Reference Data

Parameter	Unit	MELCOR Bel V	Difference*	Acceptable error 8		
Primary System						
Core power	MWth	3000	Imposed	2%		
Mass inventory in primary circuit	kg	206000	1.5%	2%		
Primary pressure (PRZ)	MPa	15.5	0.3%	0.1%		
PRZ level (collapsed)	m	6.4	0m	0.05m		
Temperature Cold Leg	К	561	0.9%	0.5%		
Temperature Hot Leg	К	599	0.6%			
Temperature average	К	580	0.8%			
Mass flow rate (for each loop)	kg/s	4600	0.2%	2%		
Mass flow rate (core + core bypass)	kg/s	13800	4.0%			
Bypass core	%	4.3	0.3%	10%		
Pressure drop LP-HL	MPa	0.27	1.1%	10%		
Pressure drop core	MPa	0.17	1.1%			
Secondary System						
SG power	MW	1000	0.1%	2%		
SG vapor mass	kg	3315	2.4%	5%		
SG liquid mass	kg	44792	4.4%			
SG total mass	kg	48109	4.1%			
SG pressure	MPa	5.9	3.9%	0.1%		
SG level (collapsed)	m	12.5	0.3m	0.1m		
+ 1A/11						

# Table 4-1 Results of Steady-State Analysis

\* With respect to plant data or reference calculations

#### 4.2 <u>Transient Results</u>

The demonstration of the nodalization quality at the steady-state level does not ensure that the prediction of a transient scenario is phenomenologically correct or even that the nodalization (input deck) is error-free: transient-level nodalization qualification process is needed (e.g. 3<sup>rd</sup> step of the nodalization qualification according to 13).

The comparisons between the experimental data (in this case: results of other another qualified nodalization, i.e. the CATHARE model which was qualified against (among other) experimental data in the framework of experimental projects like PKL and ROSA) and the calculated results are carried out with the objective of:

- verifying whether or not the code simulations are capable to reproduce the relevant TH
  phenomena and processes expected during the transient, and
- providing a reliable estimation of the parameters relevant for safety analysis.

A comprehensive comparison between the calculated trends or values is performed, including the following steps:

- the comparisons between the resulting sequence of main events (see Table 4-2) and
- the comparisons between calculated time trends on the basis of the selected variables (see Figure 4-2 to Figure 4-8, APPENDIX A and APPENDIX B, Table 4-2 and Table 4-3), by visual observation of the time trends and the occurrence of the relevant phenomena, for each phase of the transient.

Although methods exist for such purpose (see e.g. [19, 20, 21), quantitative accuracy evaluation<sup>5</sup> of the code results is not addressed.

#### 4.2.1 Base Case (A)

The results of the comparison of the MELCOR calculation results against the CATHARE ones for the reference case are reported in APPENDIX A. Summary results are also reported in Table 4-3 (together with the results of the sensitivity analyses) and Figure 4-2 and Figure 4-3. The resulting sequence of main events is reported in Table 4-2.

The transient starts at T1 = 0 s with a full rupture in the main feedwater line of one SG. The rapid depressurization and emptying of the affected SG also cause the reactor trip signal and entrains the depressurization and emptying of the other SGs via the common steam header and the steam lines, till isolation of the MS lines.

The reactor trips at T2 = 50 s after the FWLB in SG-A due to the low-low SG level in one of the intact SG (imparted event). At the same instant T2, the steam lines are isolated via their main steam isolation valves (MSIVs), the RCPs are shut down (because of LOOP), the normal FW is isolated and the AFW system starts delivering water to the intact SGs with a delay of 25 s from scram. The high core decay power and the loss of primary flow cause the primary system to heat-up and pressurize leading the PRZ relief valves to open momentarily. Around 2.5 h after the onset of the accident, the mass inventory is restored in the intact SGs.

<sup>&</sup>lt;sup>5</sup> Accuracy. The known bias between a code prediction and the actual transient performance of a real facility. Definition taken from 16

The system is left to stabilize until the operator starts the cooldown by using the ADV of the intact SGs to bring the RCS to RHRS conditions. Once the RCS starts to stabilize, the pressurizer pressure control system brings the primary pressure back to about 16 MPa.

After restoration of the mass inventory in the intact SGs before T3 = 20000 s (5.5 h after the SOT), the manual cooldown starts at 12 K/h. The "perturbation" induced by the stepwise opening of the ADV of SG-B and SG-C by 5% (assumed operator action at the beginning of the cooldown phase) creates a large counter-manometric force in the rising part of the affected loop (rising part of the HL, the SG inlet plenum, and the ascending side of the U-tube).

As shown in Figure 4-2, in Loop-A, the CL temperature remains higher than the HL temperature. Consequently, counter-buoyancy forces are created and become high enough to overcome the NC driving forces in the reactor vessel. Therefore, the mass flow in the affected loop drops to almost 0 kg/s. According to MELCOR results, the NCI occurs around 14h after the initiation of the cooldown phase (this is about 7h later than in CATHARE case), see Figure 4-3. The number of SG tubes modeled, as well as the level of details of the axial nodalizations (more detailed in CATHARE) might explain the time difference in the MELCOR prediction of the NCI occurrence<sup>6</sup>. The RHRS connection temperature is reached during the simulation time span in MELCOR and not in CATHARE. At the time of the NCI occurrence the CL temperature in CATHARE is still high and the NCI prevents further cooling of the CL of the affected loop. Indeed, the earlier is the NCI occurrence, the higher is the temperature in the affected loop.

In addition to what stated above, the following conclusions about the comparison of the MELCOR calculated results against the CATHARE ones can be derived:

- The CL and HL temperatures predicted by MELCOR in the affected loop are lower than the CATHARE ones, see Figure A-1. This is a consequence of the different prediction of the time of NCI occurrence (i.e. about 7h later in MELCOR).
- The CL and HL temperatures in the other loops of both MELCOR and CATHARE are very similar up to the time of NCI occurrence in CATHARE, discrepancies increase with the transient progression, see Figure A-2 and Figure A-3. It seems that MELCOR ADV capacity is lower than the one used in CATHARE code.
- The mass flow rates comparison reported in Figure A-4 shows very good agreement for the unaffected loops. Discrepancies are experienced in the affected loop, but the trend is very similar. The higher mass flow rate predicted by MELCOR might be a reason for the discrepancies in the time of NCI occurrence. It is noted that the same resistance and RCP coast-down curve is adopted for all three loops as the one used in CATHARE code.
- The ADV opening fraction is based on the temperature curve issued from the output of CATHARE, implemented as input parameter by means of CF in MELCOR, see Figure A-5. It is not surprising that the results are very similar: minor differences might be due to different initialization of the CF.
- Core temperatures are very similar: differences at the end of the transient are consistent with the ones experienced in the CL and HL temperatures in the unaffected loops, see Figure A-6.
- The analyzed plant is a "cold reactor vessel head" type, this is correctly reproduced by MELCOR calculations where the CL temperature equals the UH temperature during steady-state. MELCOR and CATHARE transient results show similar trends, and the behavior is judged satisfactory for the purpose of the analysis, see Figure A-7. No

<sup>&</sup>lt;sup>6</sup> The same time of occurrence of NCI (i.e. earlier) predicted by CATHARE can be achieved also by MELCOR by increasing the pump resistance or the cooling rate.

changes are performed in the MELCOR model, the results being compliant with the steady-state specifications and the transient differences are minor.

- The behavior of the CVCS is almost identical for both MELCOR and CATHARE cases. It is noted that in MELCOR the system is modeled (charging, letdown and pump seal injection: to maintain the water level in the pressurizer and the pump seals injection), and not imposed, see Figure A-8.
- The PRZ behavior shows some discrepancies which increases during the transient, but they are considered acceptable considering the modeling differences and the intent of the calculations (see Figure A-9).
- The SG secondary side pressures (Figure A-10), levels (Figure A-11), masses (Figure A-12, Figure A-13, Figure A-14) are very similar, confirming the adequacy of the MELCOR modeling of the SG for the intended purpose<sup>7</sup>, notwithstanding the more simple modeling approach. The major discrepancies are experienced for the SG heat exchange (Figure A-15) and the discrepancies increase with the transient progression. This is anyway consistent with the temperatures predictions already discussed, where reverse flow is predicted in the affected primary loop in CATHARE but not in MELCOR.
- Core power is imposed by a CF in both MELCOR and CATHARE cases, see Figure A-16, and it is reported there for the sake of completeness.

#### 4.2.2 Cases B: Impact of Cooling Rate on NCI Occurrence

For the case B1, the base case cooldown rate is decreased by 2 K/h: thus a cooldown rate of 10 K/h is considered. This is the only modification in the MELCOR input deck. In this case NCI occurrence is not predicted and RHRS connection temperature is achieved in both MELCOR and CATHARE predictions, see Figure 4-4 and Table 4-3. The results of MELCOR calculations seem to be correctly reproducing the expected CATHARE results.

For the case B2, cooldown rate is increased by 2 K/h: thus a cooldown rate of 14 K/h is considered. Figure 4-5 and Table 4-3 show an earlier time of NCI occurrence with respect to the reference case.

Regarding the impact of the cooling rate on NCI occurrence, the following conclusions can be drawn:

- Reducing the cooling rate might prevent NCI occurrence in the inactive loop.
- Increasing the cooling rate, in case NCI is predicted, has an impact on the time of NCI occurrence, which in turn impacts the temperature in the affected loop: the higher is the cooldown rate, the earlier NCI occurrence is predicted, the higher is the temperature in the affected loop.

#### 4.2.3 Cases C: Impact of Decay Heat (or Time After Scram) on NC(I) Transition

Decay heat level (or time after scram) strongly influences the NC(I) transition: using higher decay heat power is not conservative with respect to the NCI occurrence. In fact, the core power has a strong effect on the driving forces balance and consequently on the NCI time of occurrence. Therefore, for cases C the base case decay heat level is increased in conformity with the conservative assumption related to 20% of the ANS79 decay heat level and by adopting the same cooling rate of the base case. In this case, no NCI is observed, see Figure 4-6 and Table 4-3.

<sup>&</sup>lt;sup>7</sup> Severe accident analysis

As shown in Figure 4-7 and Table 4-3, by adopting higher decay heat value, transition NC(I) is experienced at higher cooling rate with respect to the base case. Indeed, also in this case the occurrence of NCI for a difference of 2 K/h in the cooldown rate might impact reaching or not the RHRS connection temperature at the end of the transient, with the only modification of the cooldown rate:

- A continuous cooldown rate of 26 K/h leads to NCI.
- With the only modification of the cooldown rate with respect to the previous case, a continuous cooldown rate of 24 K/h does not lead to NCI.

Furthermore, the following general conclusions are also derived:

- In case NCI does not occur, cooling rate has a minor impact on the mass flow rate and temperature predictions at the end of the cooling rate up to the end of the transient (i.e. the values of these quantities at the end of the transient of different cases are very similar).
- The same considerations of other cases reported above can be drawn in case of NCI occurrence (i.e. the higher the cooling rate, the earlier the NCI occurrence, the higher the temperature in the affected loop, which might reach or not the RHRS connection temperature).

For the sake of completeness (not reported in this study) the CATHARE results with high decay heat experience the transition NC(I) between 12 K/h and 14 K/h. MELCOR can reproduce such results by a RCP resistance factor of 5.80e-4. However it is supposed that the difference is mainly due to the degree of detail of the used nodalization by the two codes. On one hand, MELCOR uses coarse meshes for representing the plan systems. On the other hand, CATHARE code uses detailed plant nodalization based upon hundred thousand nodes, and more particularly the SG nodalization on the primary and secondary side.

#### 4.2.4 Cases D: Impact of RCP Resistance Set to Zero on NC(I) Transition

Sensitivities on the pump resistance set to zero are reported in Figure 4-8 and Table 4-3. Also without considering the pump resistance, MELCOR is able to predict the occurrence of the transition NC(I), experienced at higher cooling rate with respect to the base cases. Indeed, also in this case the occurrence of NCI with a difference of 2 K/h in the cooldown rate might impact reaching or not the RHRS connection temperature at the end of the transient, with the only modification of the cooldown rate:

- A continuous cooldown rate of 36 K/h leads to NCI.
- With the only modification of the cooldown rate with respect to the previous case, a continuous cooldown rate of 34 K/h does not lead to NCI.

This sensitivity study evidences the importance of implementing the resistance factor in the input deck and that NCI occurrence could be impacted by the nodalization assumptions (the nodalization of the U-tubes with MELCOR should be more detailed). Indeed using a coarse nodalization (as it is the case in MELCOR) could lead to higher value of the minimal value of the cooldown rate that leads to NCI [1]. It is worth to mention that further studies are needed to better understand the impact of this (among others) modeling assumptions (i.e. RCP resistance, and nodalization) on the results.

#### 4.2.5 Single-Phase NC: Case E

Case E investigates the capabilities of the MELCOR code in reproducing the experimental data related to the NC flow cooling regime. The results of case E are reported in APPENDIX B. It is observed that MELCOR calculation predicts well the different phases of the transient analyzed:

- The discrepancy between the CATHARE and MELCOR calculation results for the stable NC phase is within 4 °C in terms of temperature prediction in the loops and about 2 °C in terms of temperature difference, see Figure B-1, Figure B-2 and Figure B-3.
- The loop mass flow rate predictions are also very similar between the two codes, see Figure B-4 and Figure B-5, the pump coast-down modeling being similar (see Figure 2-1).
- The discrepancy between the code results for the stable NC phase is within 3 °C in terms of temperature prediction in the core, see Figure B-6.
- The core bypass and core flow rate predictions are also very similar between the two codes, see Figure B-7 and Figure B-8.

The observed agreement between the MELCOR and CATHARE calculation results is considered satisfactory, taking into account possible discrepancies of the conversion of the plant data in the codes input decks, the measurement uncertainties and the adopted boundary conditions.

Therefore, this comparative analysis confirms the capability and suitability of the 3-loop MELCOR input deck without additional modifications with respect to the reference cases (i.e. the only modifications with respect to the base cases are the imparted invents to simulate the transient), to correctly predict single-phase natural circulation phenomena.

#	Event description	CATHARE [s]	MELCOR [s]	Note
1	FWLB in SG-A	0	0	T1 Imposed
2	Depressurization and emptying of	0-50	0-50	
	all SGs			
3	Reactor trip	50	50	T2 Imposed
4	AFW to SG-B and SG-C	50	50	
5	MSIVs closed	50	50	
6	Shutdown of RCPs due to LOOP	50	50	
7	SG-B and SG-C refilling and RCS stabilization	50-20000	50-20000	
8	Operator starts cooldown at prescribed cooldown rate using ADV of SG-B and SG-C	20000	20000	T3 Imposed
9	Cooldown to RHRS entry conditions	20000-70000	20000-70000	
10	NCI	44750	69300	
		(T <sub>HL</sub> A: 492K)	(T <sub>HL</sub> A: 438K)	
11	End of calculation	80000	80000	T4 Imposed

#### Table 4-2 Base Case: Resulting Sequence of Main Events

#### Table 4-3 Summary of MELCOR Results

Cases	Cooldown Rate [K/h]	NCI occurrence	NCI time [s]	T <sub>HL</sub> affected loop at NCI [K]*	Note		
BC	12	YES	69300	438	Base Case		
B1	10	NO	-	-			
B2	14	YES	49600	468			
C1	12	NO	-	-	Cons. Decay heat		
C2	24	NO	-	-	Cons. Decay heat		
C3	26	YES	34600	486	Cons. Decay heat		
C4	28	YES	30960	504	Cons. Decay heat		
D1	34	NO	-	-	RCP resistance 0		
D2	36	YES	31620	468	RCP resistance 0		
* RHRS connection temperature is 450 K							



Figure 4-2 Base Case: MELCOR and CATHARE CL and HL Temperatures



Figure 4-3 Base Case: MELCOR and CATHARE CL Temperatures and Mass Flow Rates



Figure 4-4 Case B1: MELCOR and CATHARE CL Temperatures and Mass Flow Rates



Figure 4-5 Cases B: MELCOR CL Temperatures and Mass Flow Rates, Sensitivity Study on Cooling Rate



Figure 4-6 Cases C: MELCOR CL Temperatures and Mass Flow Rates, Impact of Decay Heat on NCI Occurrence



Figure 4-7 Cases C: MELCOR CL Temperatures and Mass Flow Rates, Sensitivity Study on Decay Heat



Figure 4-8 Cases D: MELCOR CL Temperatures and Mass Flow Rates: Impact of RCP Resistance Set to Zero on NCI Occurrence

# 5 CONCLUSIONS

MELCOR is the reference code used by Bel V for SA analysis, and, to date, it has been mainly used in the framework of the Bel V R&D program: The current study focuses on the capabilities of the MELCOR Bel V plant model to simulate NC(I) phenomena during asymmetric cooldown transients. Under accident conditions with LOOP, NC constitutes the main mechanism for core heat removal of a nuclear PWR. In certain asymmetric cooling circumstances during the cooldown phase, single-phase NCI could occur as a consequence of an imposed cooldown rate by the operator.

A model of a 3-loop 1000 MWe PWR has been developed for MELCOR 1.8.6 code version. It has been afterwards converted for MELCOR 2.1 and finally run with MELCOR 2.2 code version. The model was assessed for steady-state calculations by carrying out comparison studies against reference operating values of NPP data and other reference calculations e.g. CATHARE in this case. However, steady-state qualification does not guarantee the capability to reproduce expected transient scenarios, that's why transient analyses are performed.

Code-to-code comparisons are performed thanks to the availability of similar studies performed by means of the best estimate TH system code CATHARE. Such comparison activities are fundamental for the planned use of MELCOR for the verification of safety analyses of Belgian nuclear installations and accident management and to increase confidence in the calculated results.

For this purpose a MELCOR/CATHARE comparison of a real plant RCP trip transient simulation was performed. This is one of the steps in the Bel V MELCOR model validation matrix. The assessment study confirms the capability and suitability of the 3-loop MELCOR input deck to correctly predict single-phase NC phenomena.

According the achievements of the current study, the following conclusions can be drawn:

- The MELCOR simulation results can properly reproduce CATHARE outputs and the expected NCI phenomena;
  - For the base case, the minimum continuous cooldown rate that can still lead to NCI is about 12K/h (confirmed by CATHARE results).
  - For the cases with higher value of the core power decay heat (or earlier time after scram), NCI occurs with a higher minimum continuous cooldown rate of about 28K/h
- The MELCOR results show that, for a FWLB accident with LOOP, the occurrence of NCI is governed by the cooldown rate value and the decay heat levels (with a pump resistance values adapted to reproduce the CATHARE ones).

The following general messages on NC and NCI phenomena can be summarized as follow:

- Impact of cooldown rate
  - Reducing the cooldown rate might prevent NCI occurrence.
  - Increasing the cooldown rate, in case NCI is predicted, has an impact on the time of NCI occurrence, which in turn impacts the temperature in the affected loop: the higher is the cooldown rate, and the earlier NCI occurrence is predicted, the higher is the temperature in the affected (and inactive) loop.
  - In case NCI does not occur, cooldown rate has a minor impact on the mass flow rate up to the end of the transient.

- Impact of decay heat (or time after scram):
  - The higher is the decay heat (or the earlier is the time after scram), the higher is the minimal value of the cooldown rate without experiencing NCI.
  - It is worth noticing that implementing "conservative" power is not conservative with respect to the NCI occurrence: the lower is the decay heat, the lower is the cooldown rate that leads (in certain conditions) to NCI occurrence
- Implementing the pump resistance factor in the MELCOR model is important, but it is not necessary to experience the NCI phenomenon (i.e. NCI is experienced also without the RCP resistance).

Regarding the model development, further studies might be carried out addressing the impact of the RCP modeling as well as the RCP resistance factors on NCI prediction (depending on interest and availability of resources). In addition, since CATHARE studies showed (among other) the impact on the NCI occurrence of a detailed nodalization and more particularly the SG nodalization, similar studies might be envisaged also for MELCOR. This might explain the time difference in the MELCOR prediction of the NCI occurrence.

Regarding further comparative analyses, further assessment of the Bel V MELCOR model by using insights from the PKL, ROSA, other tests or plant available data, in conjunction with activities carried out for thermal-hydraulics is under consideration. This might include extending the comparative analyses to two phase flow conditions. In parallel, it is also worth noticing that transient analyses after fuel failure are already ongoing.

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### APPENDIX A RESULTS OF BASE (A) (12 K/H)

The MELCOR results are reported with continuous lines, the CATHARE results in dotted lines.



Figure A-1 Base Case: Loop A Temperatures: CL (Blue) and HL (Red) Temperatures



Figure A-2 Base Case: Loop B Temperatures: CL (Blue) and HL (Red) Temperatures



Figure A-3 Base Case: Loop C Temperatures: CL (Blue) and HL (Red) Temperatures



Figure A-4 Base Case: Loops Mass Flow Rates: Loop A (Blue), Loop B (Red) and Loop C (Green)



Figure A-5 Base Case: ADVs and SVs Opening Fractions (Resulting from the Imposed Cooldown Curve from CATHARE)



Figure A-6 Base Case: Inlet and Outlet Core Temperatures



Figure A-7 Base Case: UH Temperatures and Pressures



Figure A-8 Base Case: CVCS Injection and Letdown



Figure A-9 Base Case: Pressurizer Pressures



Figure A-10 Base Case: SGs Pressures



Figure A-11 Base Case: SGs Levels



Figure A-12 Base Case: SG-A Mass of Water Pool, Vapor and Total



Figure A-13 Base Case: SG-B Mass of Water Pool, Vapor and Total



Figure A-14 Base Case: SG-C Mass of Water Pool, Vapor and Total



Figure A-15 Base Case: Heat Exchange in SGs



Figure A-16 Base Case: Core Power





The MELCOR results are reported with continuous lines, the CATHARE results in dotted lines.

Figure B-1 Natural Circulation Study: Loop A Temperatures: CL (Blue) and HL (Red) Temperatures



Figure B-2 Natural Circulation Study: Loop B Temperatures: CL (Blue) and HL (Red) Temperatures



Figure B-3 Natural Circulation Study: Loop C Temperatures: CL (Blue) and HL (Red) Temperatures



Figure B-4 Natural Circulation Study: Loops Mass Flow Rates: Loop A (Blue), Loop B (Red) and Loop C (Green)



Figure B-5 Natural Circulation Study: Loops Mass Flow Rates: Loop A (Blue), Loop B (Red) and Loop C (Green) - Zoom



Figure B-6 Natural Circulation Study: Core Temperatures



Figure B-7 Natural Circulation Study: Core Bypass (Blue) and Core (Red) Mass Flow Rates



Figure B-8 Natural Circulation Study: Core Bypass (Blue) and Core (Red) Mass Flow Rates - Zoom

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11. ABSTRACT (200 words or less) This document describes the analysis carried out with MELCOR 2.2 computer code of the natural circulation (interruption) phenomena during asymmetric cooldown transients in a 3-loop nuclear power plant (NPP) configuration. Indeed, thermal-hydraulic analysis is an important issue for severe accident codes, it constitutes the starting point of the analysis before the occurrence of the core degradation.		
The considered accident scenario consists in a feedwater line break (FWLB) combined with loss of offsite power (LOOP) in a generic 1000 MWe 3-loop pressurized water reactor (PWR).		
For this study, a Bel V MELCOR 3-loop PWR model has been developed. The main goal is to verify the capabilities of the MELCOR code in predicting the establishment of the natural circulation flow regime, the eventual occurrence of the natural circulation interruption (NCI) phenomena and to compare to the results from an equivalent analysis performed using the thermal-hydraulic system code CATHARE. The activity is completed by carrying out sensitivity analyses in order to identify the key MELCOR modeling parameters.		
The calculation results confirm the Bel V MELCOR 3-loop plant model capability and suitability for its intended purpose in support of regulatory activities.		
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